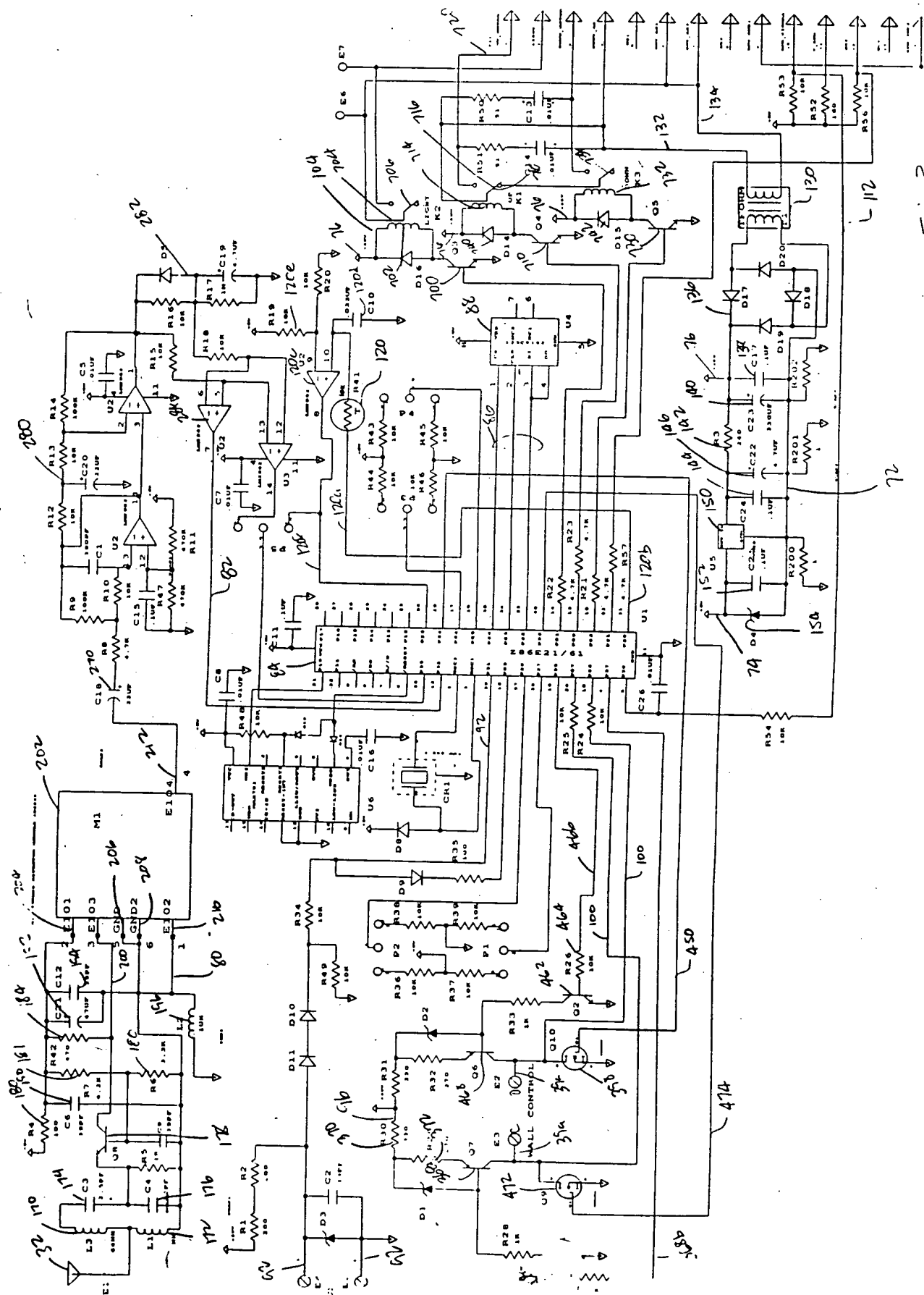


Fig. 2



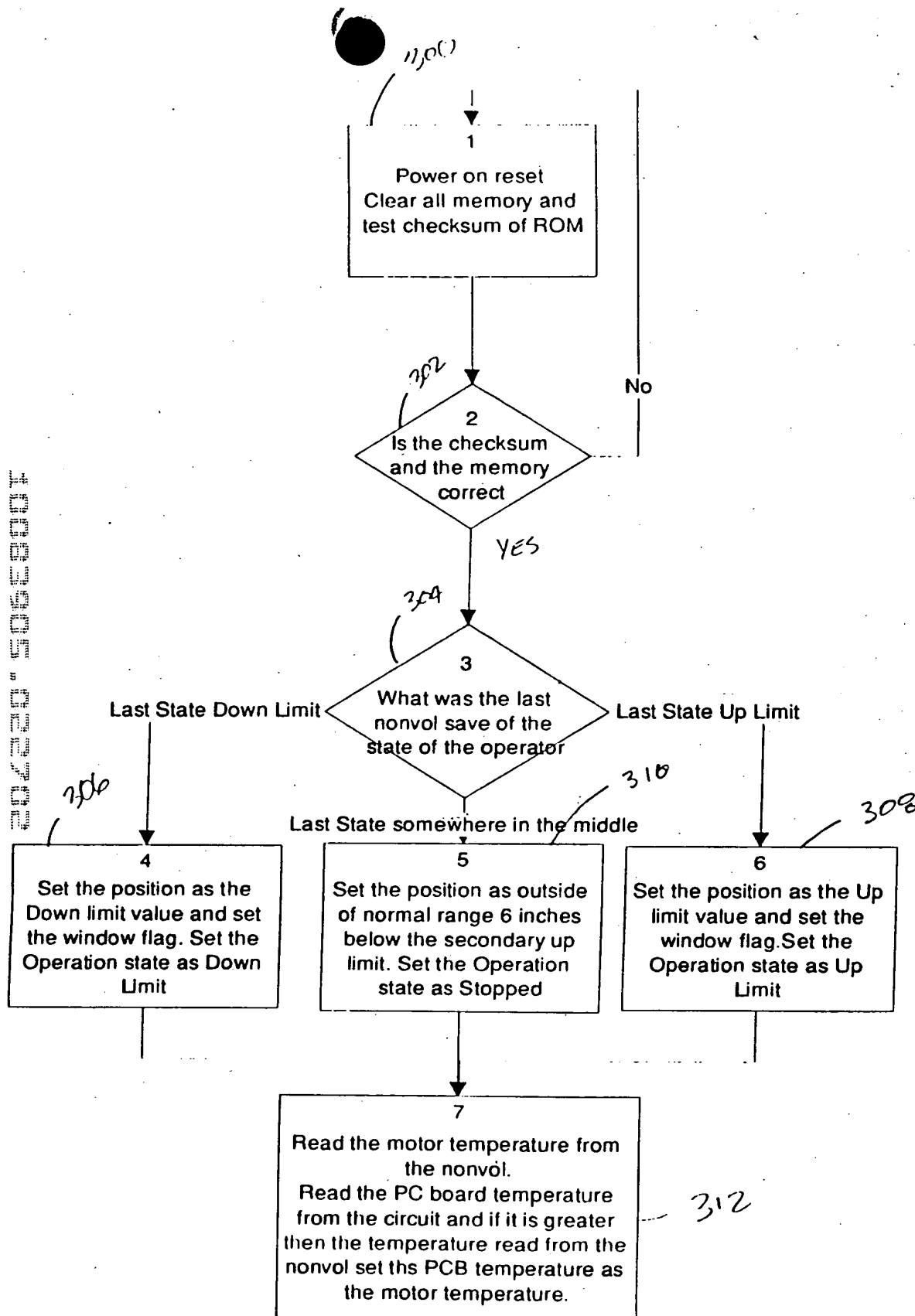
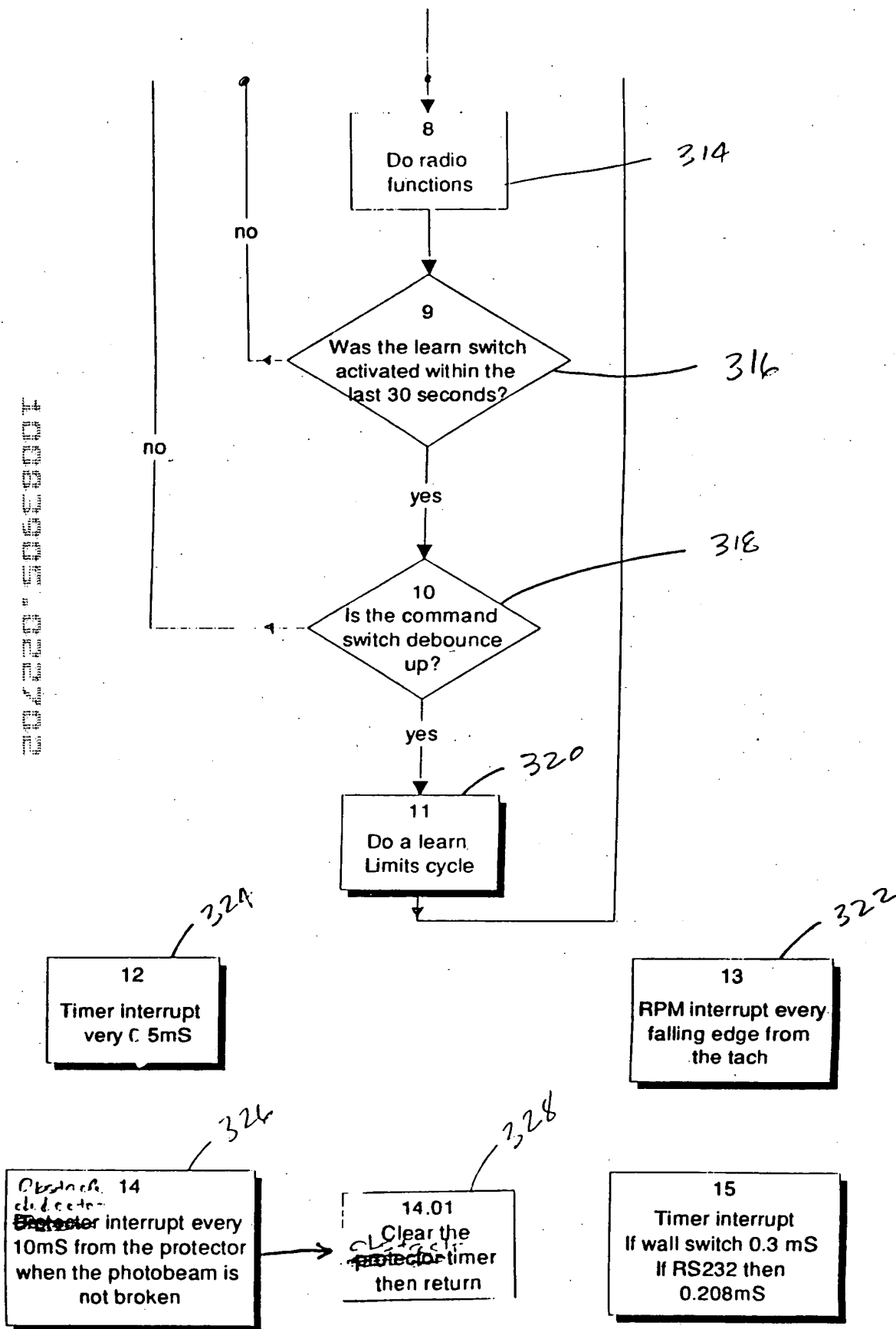


Fig. 5A

304320 6053301



```

graph TD
    11.01[11.01  
Set the max  
force to min] --> 11.02[11.02  
Turn off both  
motor outputs and  
delay 0.5 Seconds]
    11.02 --> 11.03[11.03  
Turn on the light and Set  
the Up motor outputs  
start the 1 second force  
ignore timer]
    11.03 --> 11.04{11.04  
Is the 1 second force  
ignore time up? and Is  
the force period longer  
then the force limit  
setting ?}
    11.04 -- No --> 11.05{11.05  
Is the command  
switch still held?}
    11.04 -- Yes --> 11.01
    11.05 -- Yes --> 11.03
    11.05 -- No --> 11.01

```

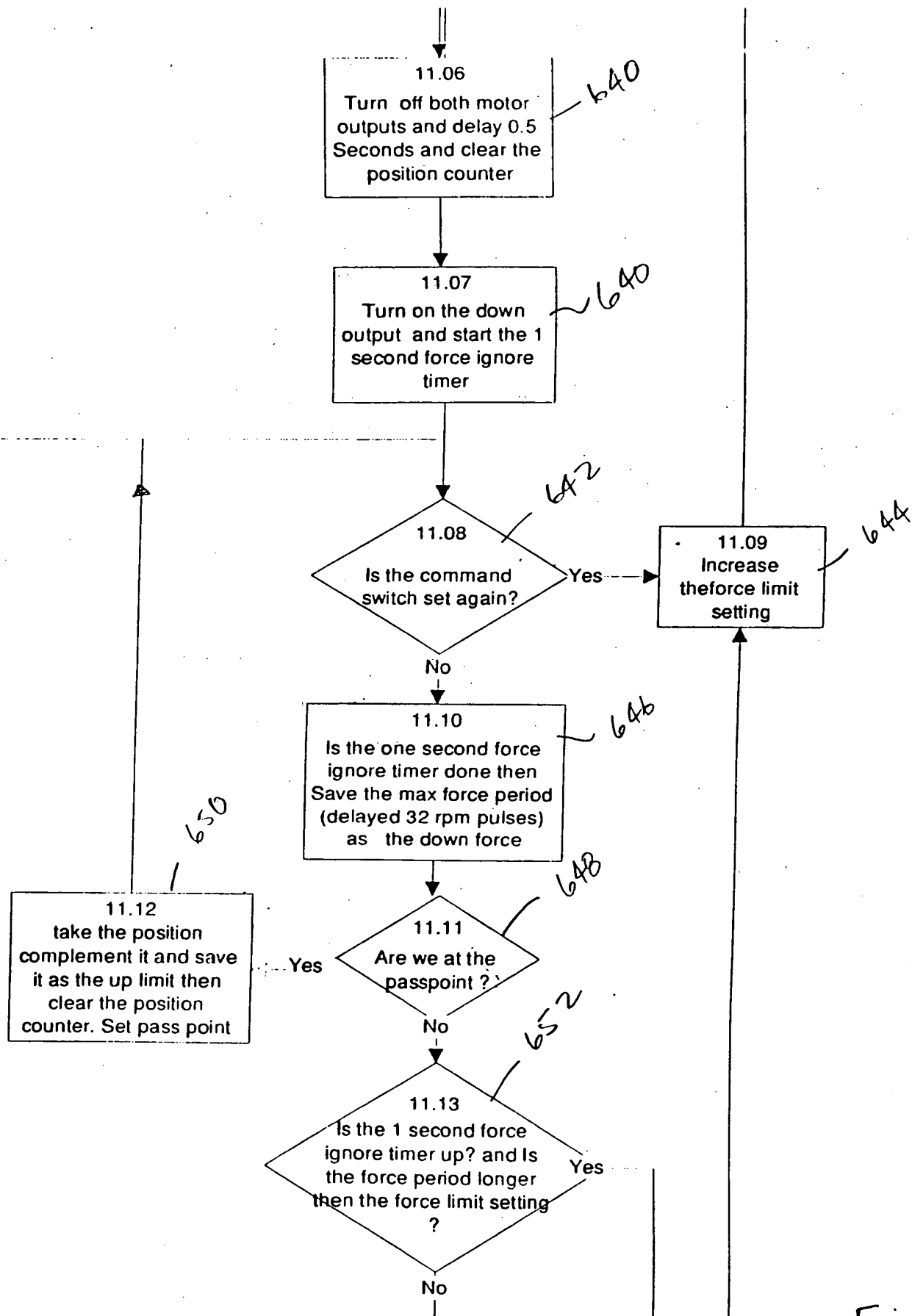


Fig. 6B

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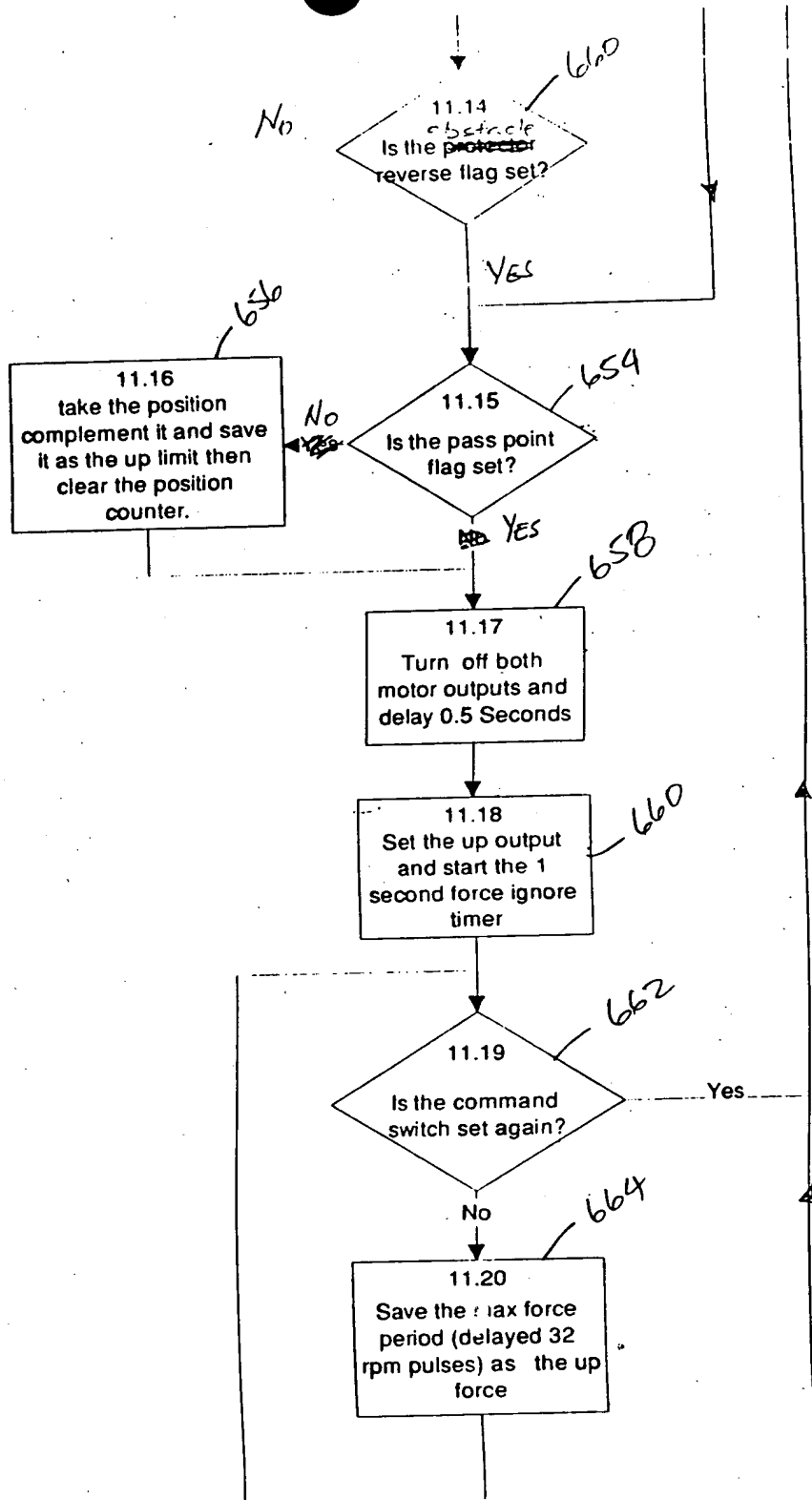


Fig. 6c

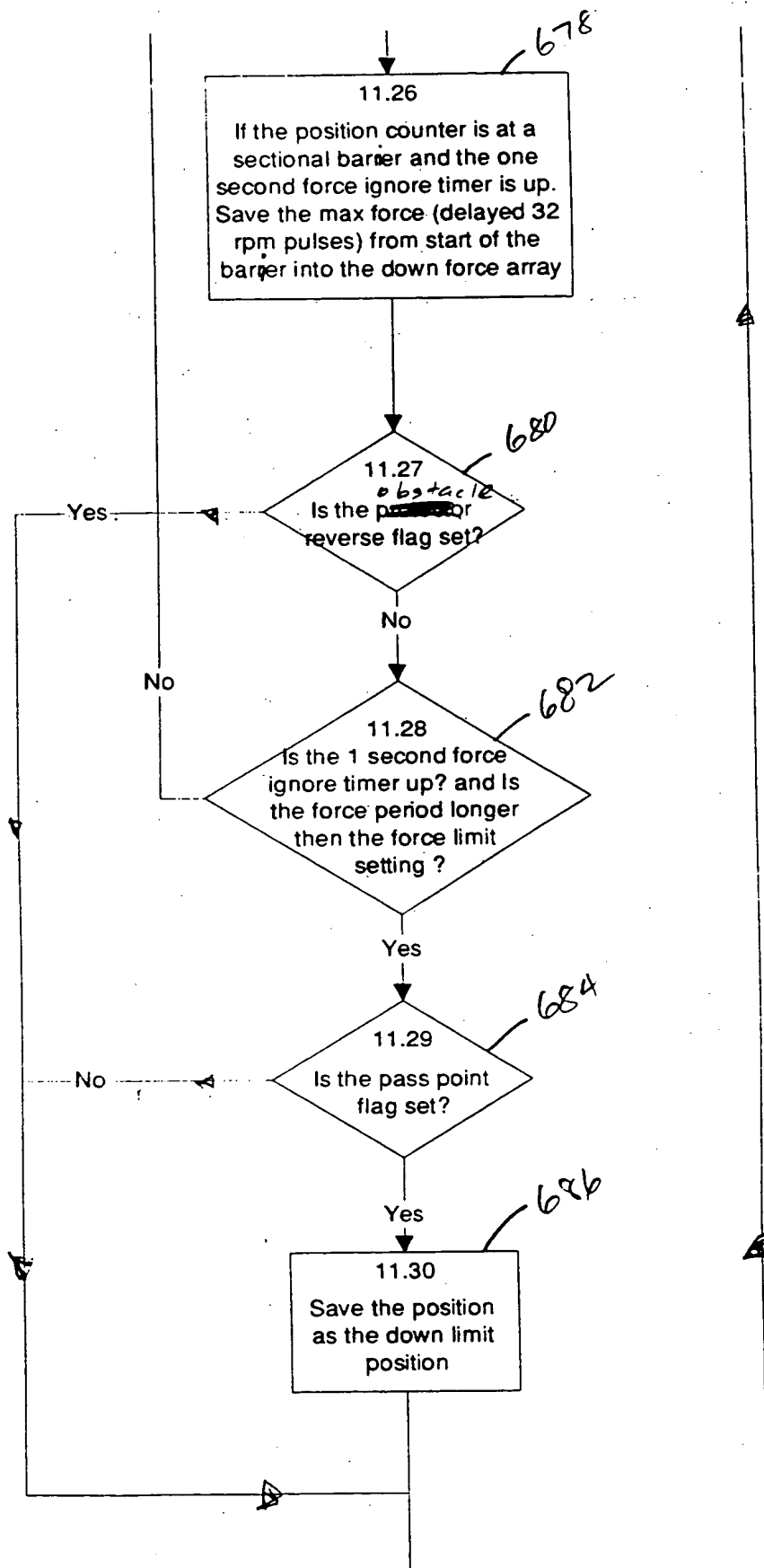


Fig. 6E

2025 RELEASE UNDER E.O. 14176

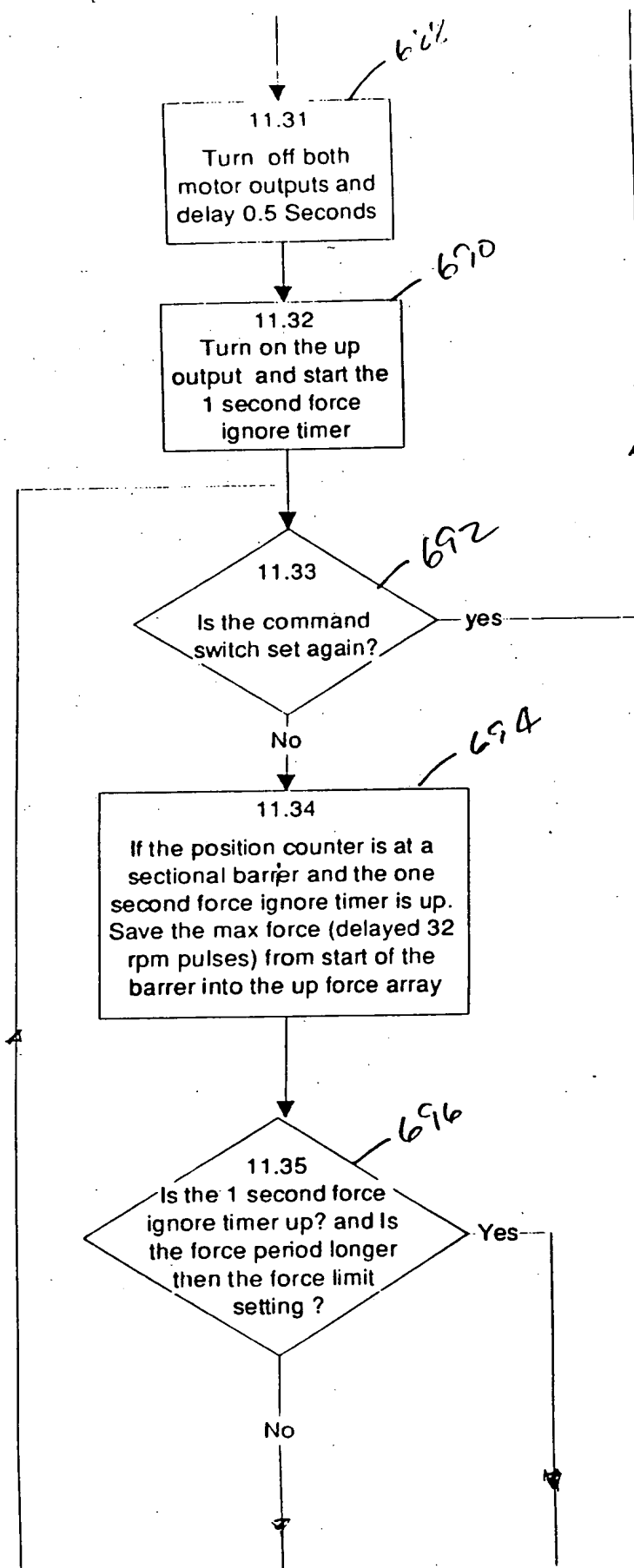
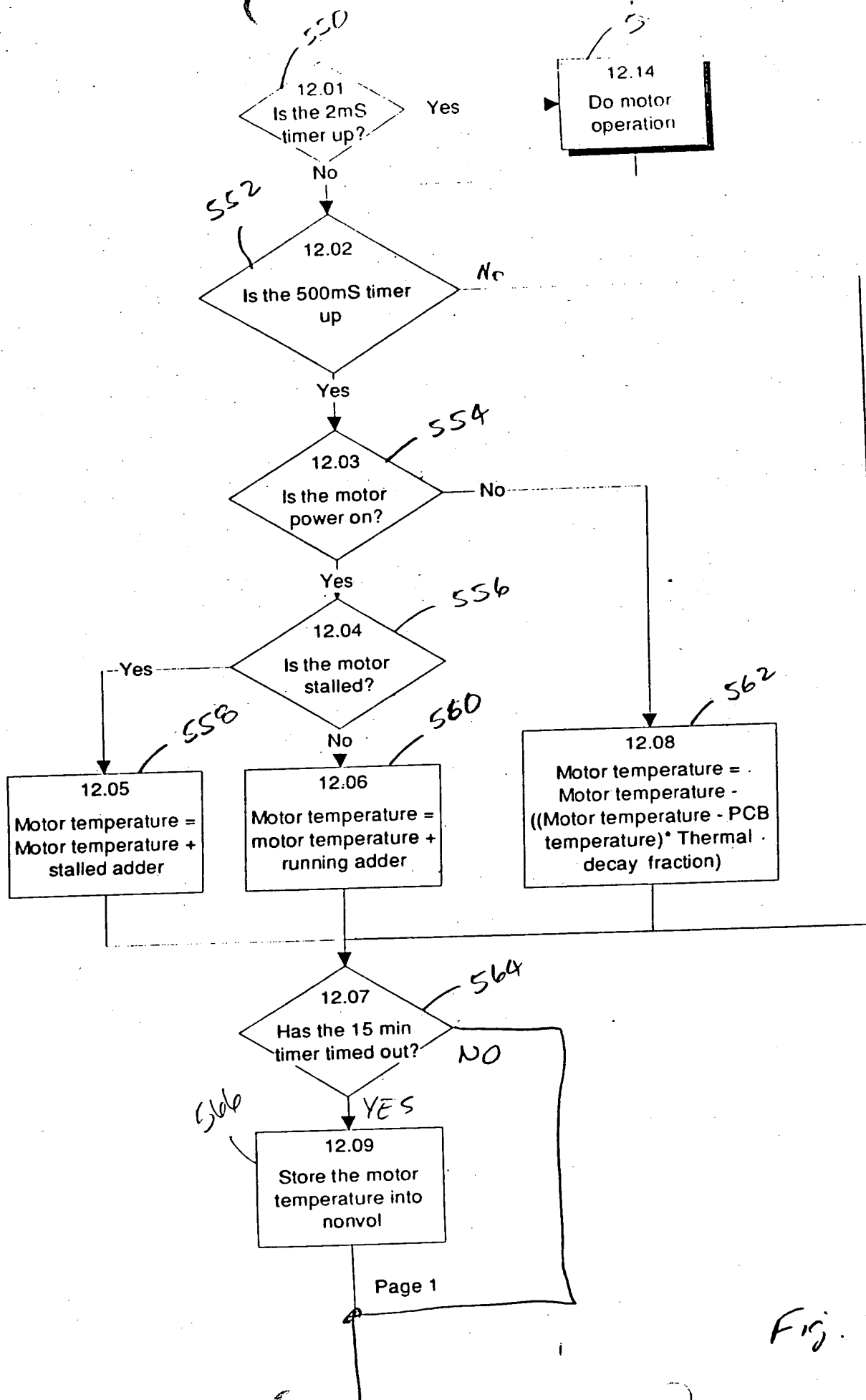
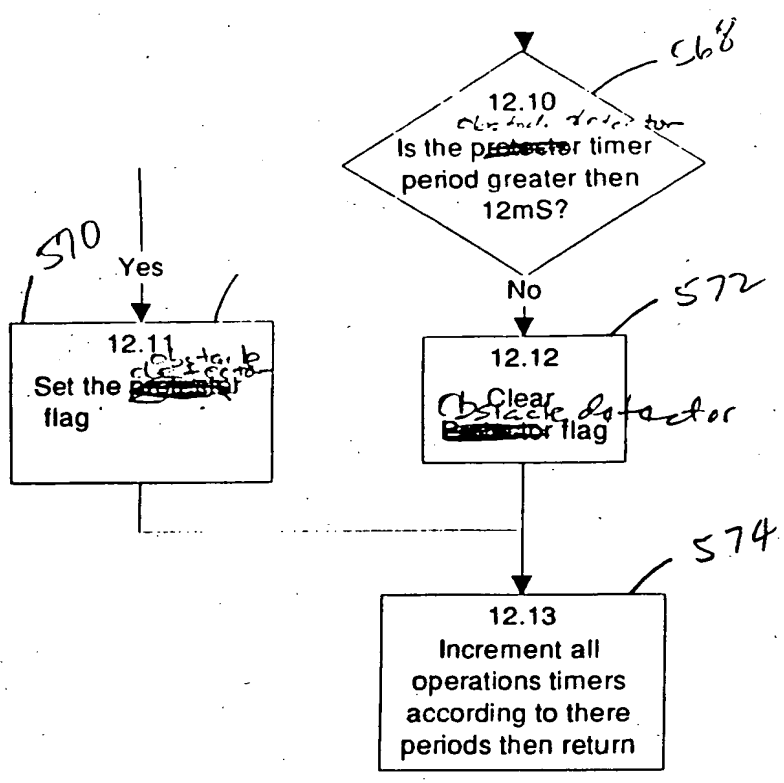


Fig. 6F



1003505 0620E



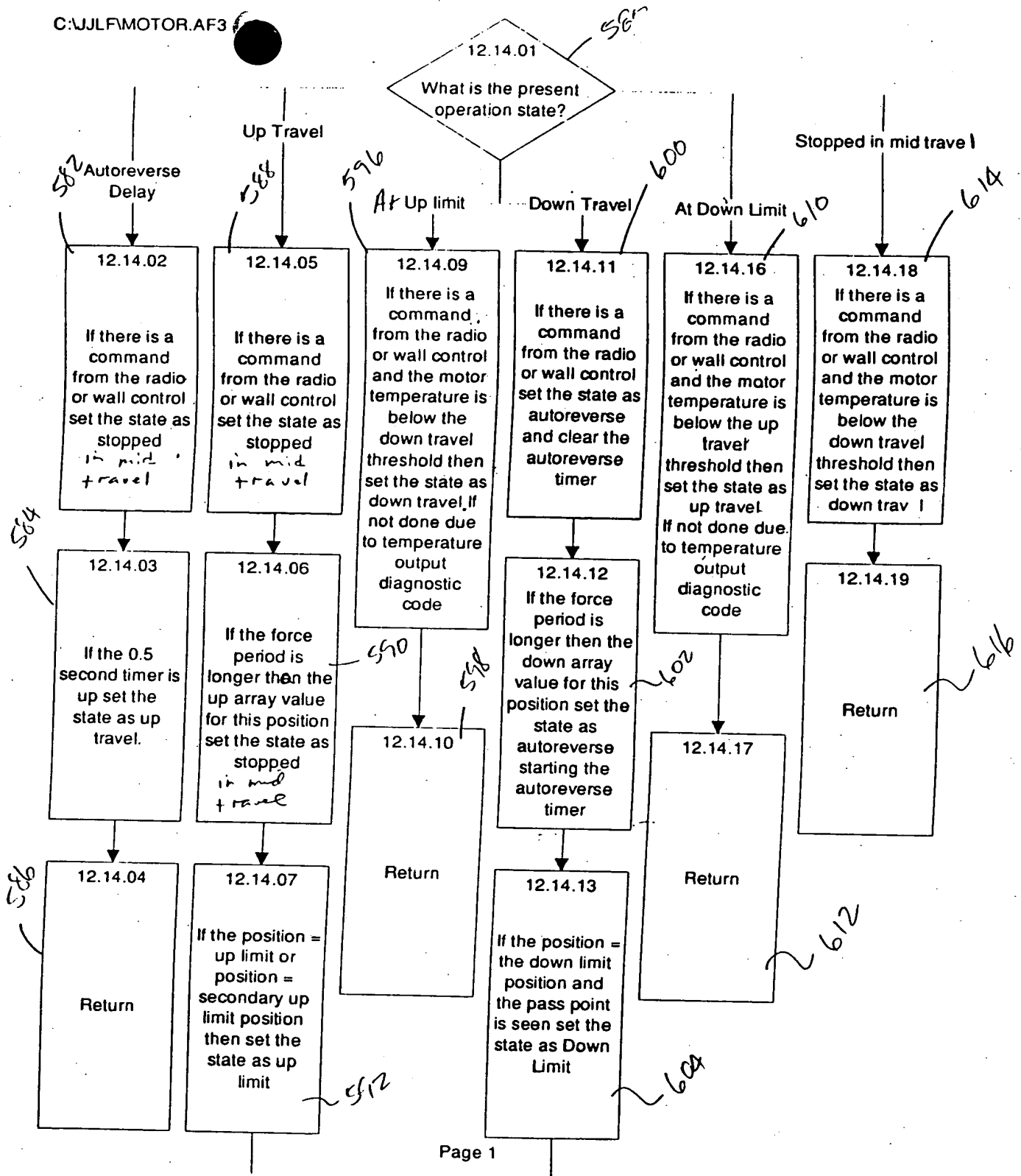
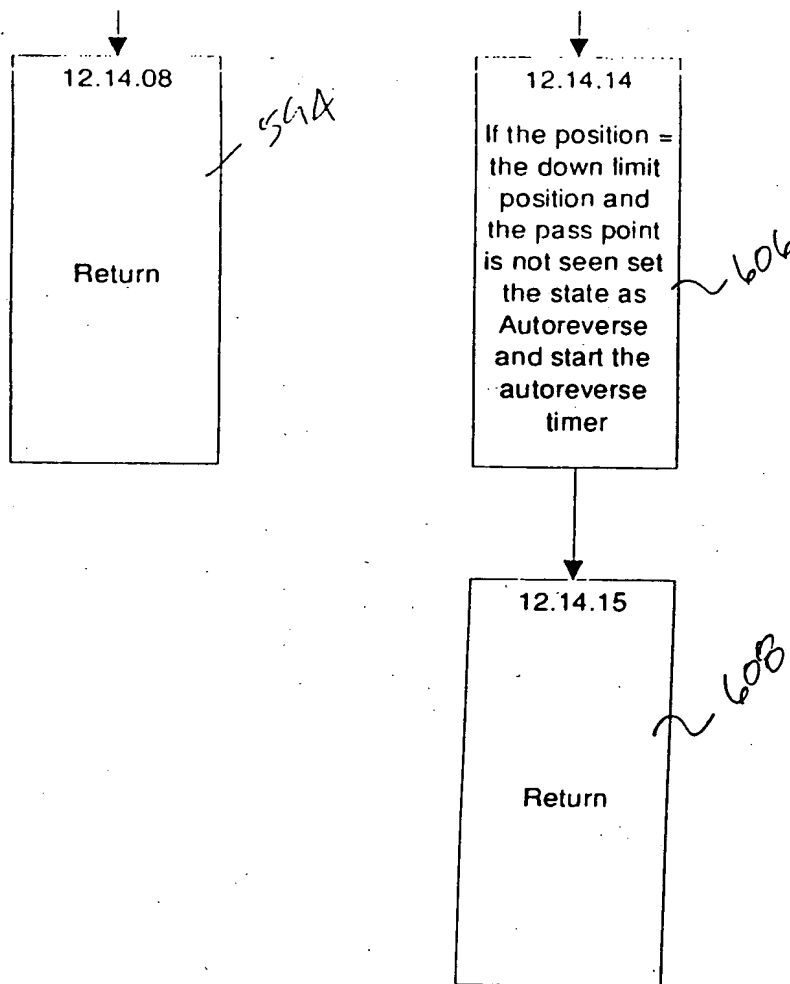
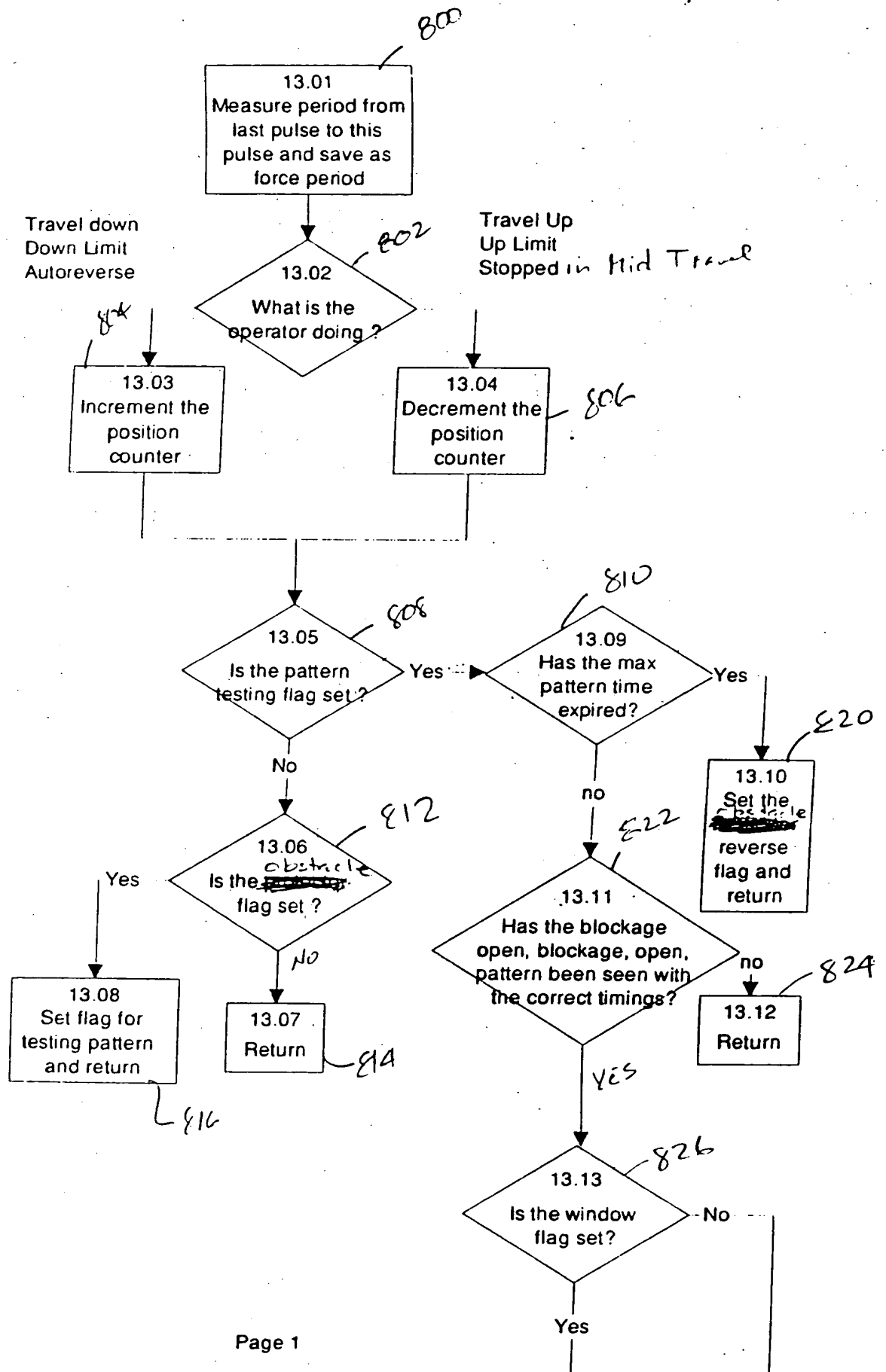
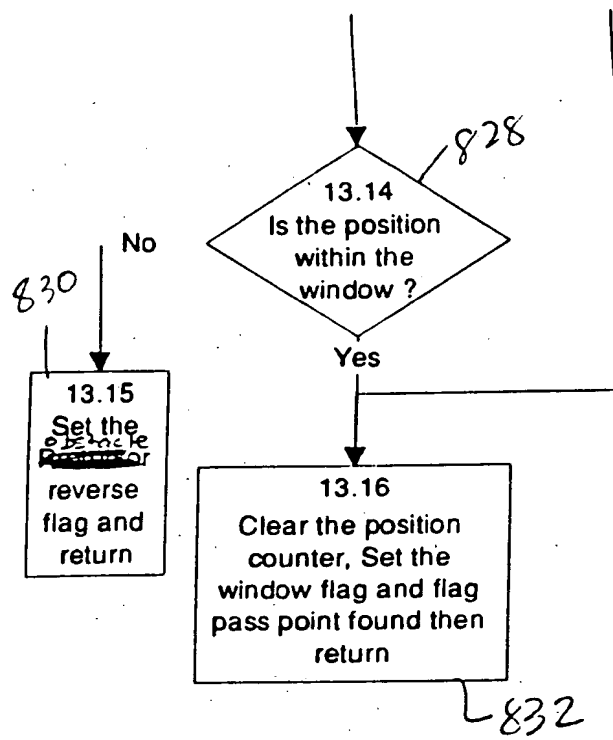


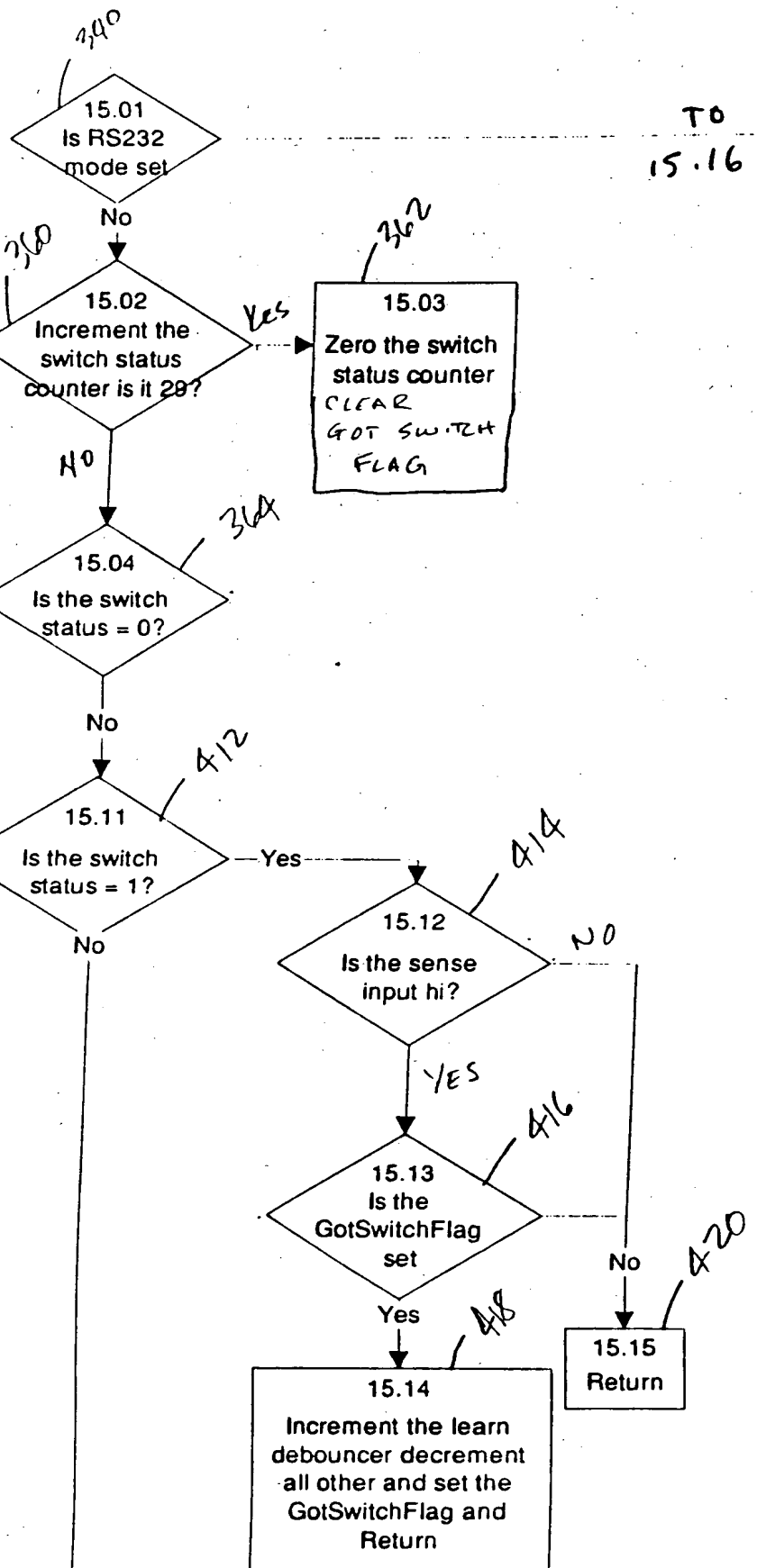
Fig. EA





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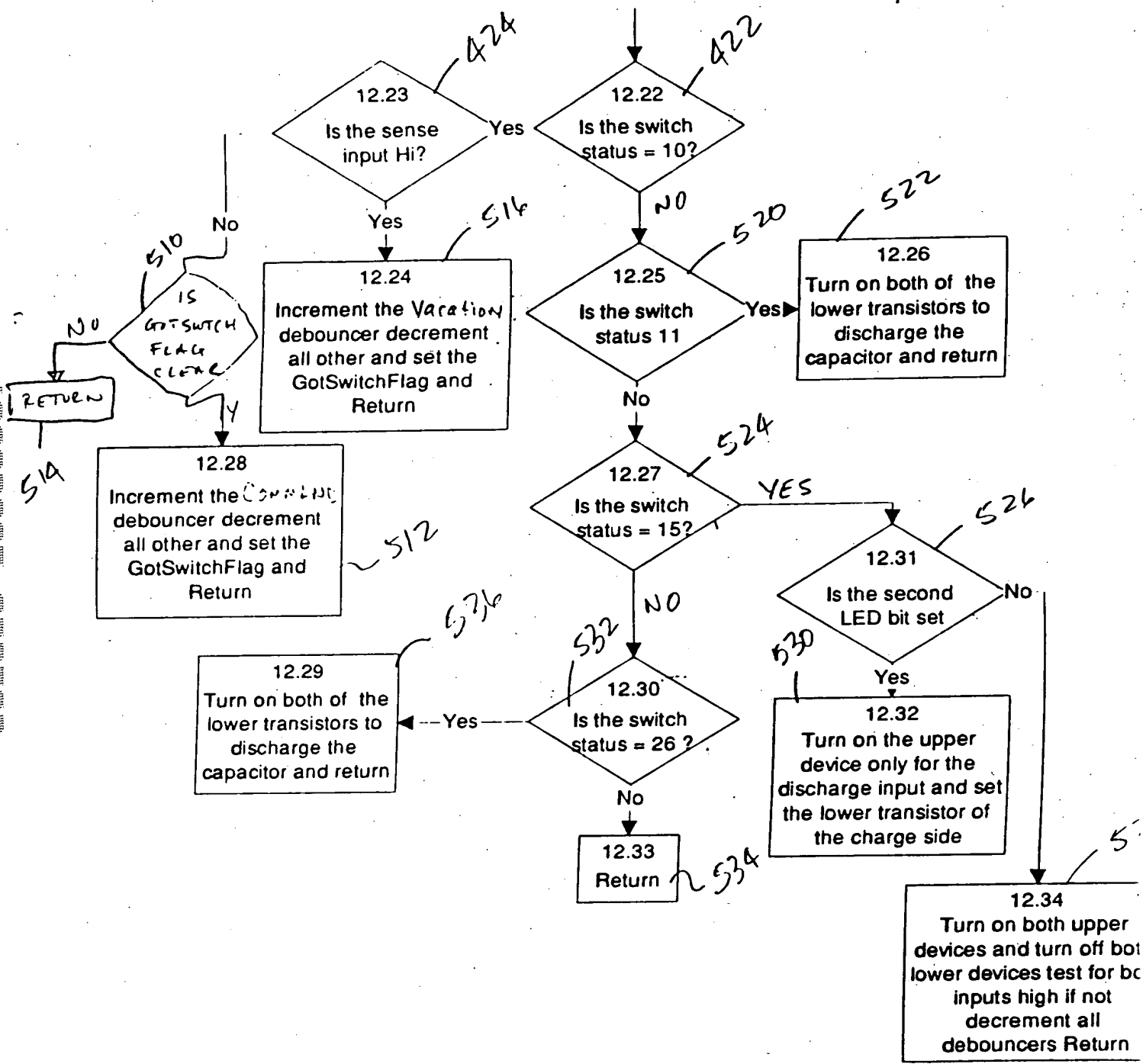


Fig. 10

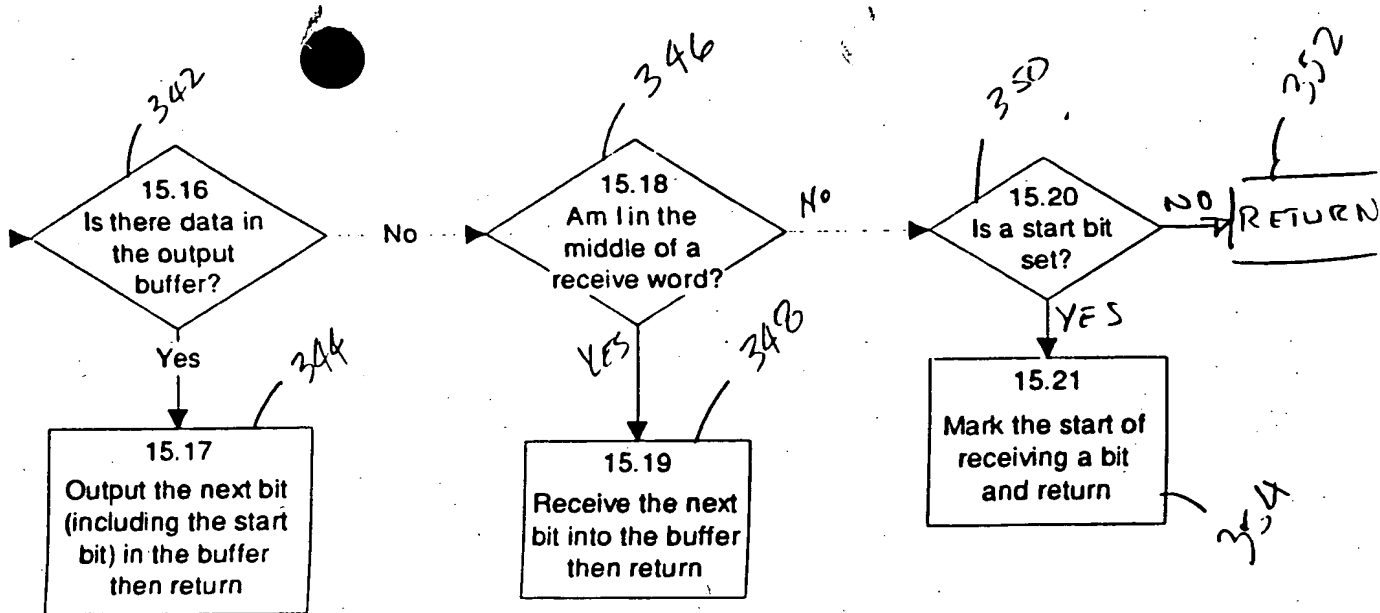


Fig. 11

